



3D Laser Scanning Options



| SCANNING TYPE | SPECIFICATIONS | | KEY PROS & CONS |
|--|--|--|--|
| <p>Static (Faro Focus S150+)</p>  | <p><u>Final Pointcloud Accuracy</u> Externals: up to +/- 3mm – 5mm Internals: up to +/- 3mm – 10mm</p> | <p><u>Range</u> Up to 150m</p> | <p><u>Pros</u></p> <ul style="list-style-type: none"> - higher accuracies compared to mobile scanning - scanner can be raised vertically on extendible tripod - structured pointclouds by default - greater distance range <p><u>Cons</u></p> <ul style="list-style-type: none"> - longer fieldwork times (higher cost) - potential line of sight issues - larger data sets |
| | <p><u>Final Pointcloud Deliverables</u> Structured pointcloud (with embedded photo-spheres) Unstructured pointcloud (without photo-spheres)</p> | <p><u>Normal Pointcloud Density</u> 2mm – 5mm (decreases for longer distances from scanning traverse)</p> | |
| <p>Mobile (VLX-3)</p>  | <p><u>Final Pointcloud Accuracy</u> Externals: up to +/- 15mm Internals: up to +/-10mm</p> | <p><u>Range</u> Up to 50m</p> | <p><u>Pros</u></p> <ul style="list-style-type: none"> - faster fieldwork times (cost savings) - line of site issues minimised - applies noise filtering algorithm to final data set - smoother colour rendering <p><u>Cons</u></p> <ul style="list-style-type: none"> - lower accuracies compared to static scanning - unstructured pointclouds only - requires built environment for stable site geometry (i.e. no fields) |
| | <p><u>Final Pointcloud Deliverable</u> Unstructured pointcloud (without photo-spheres)</p> | <p><u>Normal Pointcloud Density</u> Default 5mm (decreases for longer distances from scanning traverse)</p> | |